

Towards apparent convergence in asymptotically safe quantum gravity

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Based on

TD, J. M. Pawłowski, M. Reichert: [arXiv:1612.07315](https://arxiv.org/abs/1612.07315)

Asymptotic safety seminar
2017-04-24



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Motivation

Examine asymptotic safety (AS) scenario using a systematic vertex expansion

- extend the expansion to the dynamical graviton four-point function
- obtain closed flow equation for the graviton propagator
- investigate convergence properties of the vertex expansion
- access different tensor structures in the flow
- technical improvement towards more quantitative results

Outline

1. Systematic vertex expansion
2. Accessing tensor structures
3. Apparent convergence
4. Summary and Outlook

Quantum Einstein gravity

Einstein-Hilbert action:

$$S_{\text{EH}}(g) = \frac{1}{16\pi G_N} \int d^4x \sqrt{g} (2\Lambda - R(g)) \quad (1)$$

gauge symmetry: diffeomorphism invariance

gauge fixing necessitates background metric \bar{g} :

- use a linear metric split $g = \bar{g} + h$
- with a flat Euclidean background $\bar{g} = \mathbb{1}$
- gauge-fixed action (with Fadeev-Popov ghosts \bar{c}, c):

$$S_{\text{gf}}(\bar{g}, h) = \frac{1}{2\xi_1} \int d^4x \sqrt{\bar{g}} \bar{g}^{\mu\nu} F_\mu F_\nu$$

$$F_\mu = \bar{\nabla}^\nu h_{\mu\nu} - \frac{1 + \xi_2}{4} \bar{\nabla}_\mu h^\nu{}_\nu$$

$$S(\bar{g}, h, \bar{c}, c) = S_{\text{EH}}(\bar{g} + h) + S_{\text{gf}}(\bar{g}, h) + S_{\text{gh}}(\bar{g}, h, \bar{c}, c) \quad (2)$$

Systematic vertex expansion

Solve Wetterich equation via vertex expansion ($\phi = (h, c, \bar{c})$):

$$\Gamma_k(\bar{g}, \phi) \approx \sum_{n=0}^N \frac{1}{n!} \Gamma_k^{(n)}(\bar{g}, \phi) \Big|_{\phi=0} \phi^n \quad (3)$$

⇒ obtain tower of coupled differential equations

- compute flow equations up to $N = 4$
- closed flow for graviton propagator

$$\begin{aligned} \partial_t \Gamma_k &= \frac{1}{2} \text{[Diagram 1]} - \text{[Diagram 2]} \\ \partial_t \Gamma_k^{(h)} &= -\frac{1}{2} \text{[Diagram 3]} + \text{[Diagram 4]} \\ \partial_t \Gamma_k^{(2h)} &= -\frac{1}{2} \text{[Diagram 5]} + \text{[Diagram 6]} - 2 \text{[Diagram 7]} \\ \partial_t \Gamma_k^{(c\bar{c})} &= \text{[Diagram 8]} + \text{[Diagram 9]} \\ \partial_t \Gamma_k^{(3h)} &= -\frac{1}{2} \text{[Diagram 10]} + 3 \text{[Diagram 11]} - 3 \text{[Diagram 12]} \\ &\quad + 6 \text{[Diagram 13]} \\ \partial_t \Gamma_k^{(4h)} &= -\frac{1}{2} \text{[Diagram 14]} + 3 \text{[Diagram 15]} + 4 \text{[Diagram 16]} \\ &\quad - 6 \text{[Diagram 17]} - 12 \text{[Diagram 18]} + 12 \text{[Diagram 19]} \\ &\quad - 24 \text{[Diagram 20]} \end{aligned}$$

Flows of fluctuation correlation functions are closed

Background flows

Non-trivial Nielsen identities (NI) connect derivatives w.r.t. background and fluctuation field:

$$\frac{\delta\Gamma_k(\bar{g}, h)}{\delta\bar{g}_i} = \frac{\delta\Gamma_k(\bar{g}, h)}{\delta h_i} + \mathcal{N}_{k,i}^{\text{gf}}(\bar{g}, h) + \mathcal{N}_{k,i}^{\text{reg}}(\bar{g}, h) \quad (4)$$

Obtain flow equations for background couplings using heat kernel methods:

$$\partial_t \bar{g} = 2\bar{g} - \bar{g}^2 f_{R^1}(\lambda_2; \eta_h, \eta_c) \quad (5)$$

$$\partial_t \bar{\lambda} = -4\bar{\lambda} + \bar{\lambda} \frac{\partial_t \bar{g}}{\bar{g}} + \bar{g} f_{R^0}(\lambda_2; \eta_h, \eta_c) \quad (6)$$

- flow of background couplings depends on couplings of the dynamical two-point functions

n -point functions

Ansatz for n -point functions ($\mathbf{p} = (p_1, \dots, p_n)$):

Fischer & Pawłowski 2009, Christiansen et.al. 2012, 2014, 2015

$$\Gamma^{(\phi_1, \dots, \phi_n)}(\mathbf{p}) = \left(\prod_{i=1}^n Z_{\phi_i}^{1/2}(p_i^2) \right) (k^{-2} g_n(\mathbf{p}))^{\frac{n-2}{2}} \mathcal{T}^{(\phi_1, \dots, \phi_n)}(\mathbf{p}) \quad (7)$$

$$\mathcal{T}^{(\phi_1, \dots, \phi_n)}(\mathbf{p}) = G_N S^{(\phi_1, \dots, \phi_n)}(\mathbf{p}; \Lambda \rightarrow k^2 \lambda_n)$$

- disentangle background and fluctuation couplings
- concentrate on tensor structures generated by gauge-fixed EH-action
- introduce level- n fluctuation couplings λ_n , $g_n(\mathbf{p})$ for each n -point function
 - λ_n describes momentum-independent part of $\Gamma_k^{(n)}$
 - $g_n(\mathbf{p})$ carries global scale- and momentum dependence
- RG-running carried by wave function renormalisations $Z_{\phi_i}(p_i^2)$
 - only appear via anomalous dimensions
$$\eta_{\phi_i}(p^2) = -\dot{Z}_{\phi_i}(p^2)/Z_{\phi_i}(p^2)$$

Systematic vertex expansion

- concentrate on transverse-traceless (TT) parts of the flow equations
 - spin-two, numerically dominant, gauge-independent
 - assume uniform wave function renormalisations
 - apply TT projectors to all external graviton legs
- evaluate momenta at the symmetric point:
 - $(n - 1)$ -simplex configuration where all angles and absolute values are the same
 - $\langle p_i, p_j \rangle = \frac{n\delta_{ij} - 1}{n - 1} p^2$
 - $\mathbf{p} \rightarrow p^2$
- use Litim regulator $r(x) = (x^{-1} - 1)\Theta(1 - x)$
 - analytic flow equations for couplings at $p^2 = 0$

Systematic vertex expansion

Summary

- vertex expansion around $\bar{g} = \mathbb{1}$ up to the graviton four-point function
- ansatz for n -point vertices:
 - tensor structures generated from gauge-fixed EH action
 - RG-running carried by Z_{ϕ_i}
 - overall momentum and scale dependence carried by $g_n(\mathbf{p})$
 - momentum independent part described by λ_n
- concentrate on transverse-traceless (TT) parts of the flow equations
- evaluate momenta at the symmetric point

Accessing tensor structures

In principle, the flow generates all tensor structures:

- tensor structures of higher curvature invariants contribute to momentum dependence of $\Gamma^{(n)}(p^2)$ via g_n and Z_{ϕ_i}
- ⇒ resolving momentum dependence allows to identify these invariants

Schematically, $R \sim h_{\text{TT}}^2 + \mathcal{O}(h_{\text{TT}}^3)$ and $R_{\mu\nu} \sim h_{\text{TT}} + \mathcal{O}(h_{\text{TT}}^2)$

For our projection scheme:

⇒ graviton three-point function:

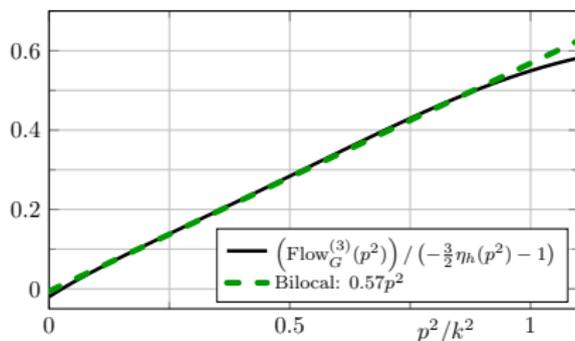
- overlap with R , $R_{\mu\nu}^2$, $R_{\mu\nu}^3$, $R^{\mu\nu} f_{\mu\nu\rho\sigma}^{(3)}(\nabla)R^{\rho\sigma}$,
 $R^{\mu\nu} R^{\rho\sigma} f_{\mu\nu\rho\sigma\omega\zeta}^{(3)}(\nabla)R^{\omega\zeta}$ tensor structures
- no overlap with $R^{n \geq 2}$ tensor structures

⇒ graviton four-point function:

- analogous to three-point function plus R^2 , $R_{\mu\nu}^4$,
 $R^{\alpha\beta} R^{\mu\nu} R^{\rho\sigma} f_{\alpha\beta\mu\nu\rho\sigma\omega\zeta}^{(4)}(\nabla)R^{\omega\zeta}$ tensor structures
- no overlap with $R^{n \geq 3}$ tensor structures

Graviton 3-point function

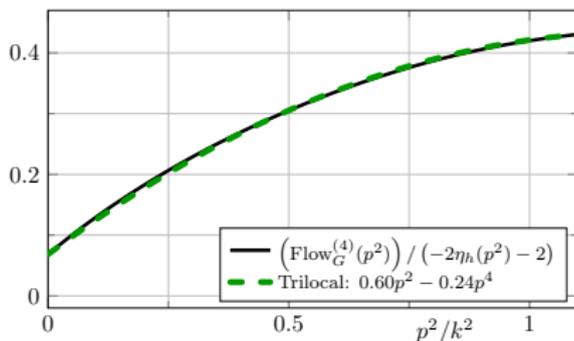
momentum dependence of the flow of the normalised three-point function ($p^2 \in [0, k^2]$, $|\lambda_n| \lesssim 1$):



- polynomial structure up to p^2
 - no signature of $R_{\mu\nu}^2$ tensor structures or others that would result in p^4 contribution
- $\Rightarrow R_{\mu\nu}^2$ can be excluded as a UV-relevant direction

Graviton 4-point functions

momentum dependence of the flow of the normalised four-point function ($p^2 \in [0, k^2]$, $|\lambda_n| \lesssim 1$):



- polynomial structure up to p^4
 - generation of p^6 contributions non-trivially suppressed
 - $R_{\mu\nu}^2$ was excluded as a UV-relevant direction \Rightarrow UV-relevant part can be attributed to R^2 tensor structures
- suggests strategy to disentangle contributions from R , R^2

In our work, we include the contribution of R^2 via the momentum dependence of $g_4(p^2)$.

UV fixed point

Look for a fixed point for $\mu = -2\lambda_2$, λ_3 , λ_4 , $g_3(p^2)$, and $g_4(p^2)$

- project onto $\Gamma^{(n)}(p^2 = 0)$ for μ , $\lambda_{3,4}$
- project bilocally at $p^2 = 0$ and $p^2 = k^2$ for $g_{3,4} = g_{3,4}(p^2) \approx g_{3,4}(k^2)$

Fixed point values and critical exponents:

$$(\mu^*, \lambda_3^*, \lambda_4^*, g_3^*, g_4^*) = (-0.45, 0.12, 0.028, 0.83, 0.57) \quad (8)$$

$$\theta_i = (-4.7, -2.0 \pm 3.1i, 2.9, 8.0) \quad (9)$$

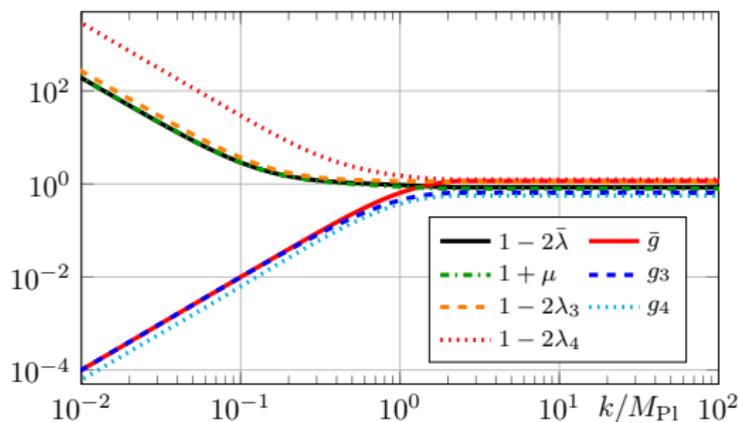
Three relevant directions, can be attributed to Λ , R , and R^2

- in agreement with previous background field approximation studies

e.g. Lauscher & Reuter 2002, Codello et.al. 2007 & 2009, Machado & Saueressig 2007, Falls et.al. 2013

IR behaviour

example trajectory connecting UV fixed point with GR:



tune \bar{g} and $\bar{\lambda}$ via solving NI in the IR:

$$\frac{\delta\Gamma(\bar{g}, h)}{\delta\bar{g}} = \frac{\delta\Gamma(\bar{g}, h)}{\delta h} \quad \text{for } \mu \rightarrow \infty \quad \& \quad k \rightarrow 0 \quad (10)$$

- couplings scale classically in the IR
 - diffeomorphism invariance corresponds to $g_n = g_3$ for $k \rightarrow 0$
- \Rightarrow fine-tuning problem

Apparent convergence

We want to estimate the quality of our truncation of the vertex expansion up to $N = 4$.

⇒ look for signatures of apparent convergence:

- compare results for different levels of the expansion, here $N = 3$ and $N = 4$
- Does the system become more stable?

UV fixed point

Compare fixed point values and critical exponents:

$N = 3$:

Christiansen, Knorr, Meibohm, Pawłowski, Reichert 2015

$$(\mu^*, \lambda_3^*, \mathbf{g}_3^*) = (-0.57, 0.095, 0.62) \quad (11)$$

$$\theta_i = (-1.3 \pm 4.1i, 12) \quad (12)$$

$N = 4$:

$$(\mu^*, \lambda_3^*, \lambda_4^*, \mathbf{g}_3^*, \mathbf{g}_4^*) = (-0.45, 0.12, 0.028, 0.83, 0.57) \quad (13)$$

$$\theta_i = (-4.7, -2.0 \pm 3.1i, 2.9, 8.0) \quad (14)$$

- fixed point values are comparable
- four-point truncation has one relevant direction more due to inclusion of R^2

Stability matrix approximation

The critical exponents are the eigenvalues of the stability matrix

$$J_{ij} = \partial_{\alpha_j} \dot{\alpha}_i$$

- need to make ansatz for higher couplings
 - here: $g_{5,6} = g_4$ and $\lambda_{5,6} = \lambda_3$ for $N = 4$
 - for $N = 3$: $g_{4,5} = g_3$ and $\lambda_{4,5} = \lambda_3$

⇒ approximation for stability matrix of the truncated flow is ambiguous

- details of the approximation should become less important for improved truncations

θ_j : identify higher couplings first, then take derivatives

$\tilde{\theta}_j$: first take derivatives, then identify higher couplings

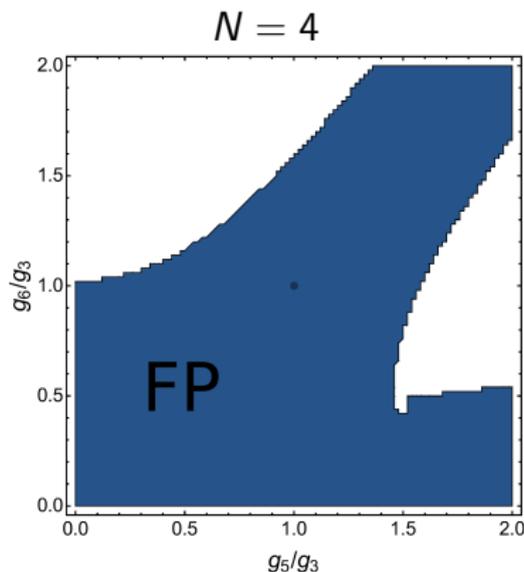
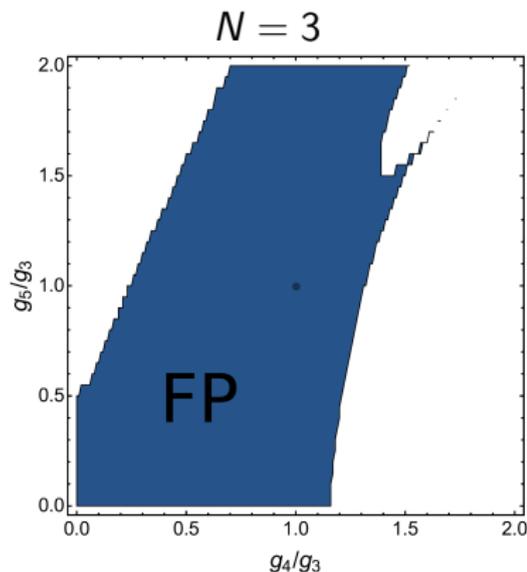
	three-point function	four-point function
θ_i	$-1.3 \pm 4.1i, 12$	$-4.7, -2.0 \pm 3.1i, 2.9, 8.0$
$\tilde{\theta}_i$	$-7.3, 3.4, 7.4$	$-5.0, -0.37 \pm 2.4i, 5.6, 7.9$

⇒ critical exponents are more stable for the improved truncation

Identification of higher couplings

Identification of higher order couplings is not fixed

- Which choices still allow for the existence of the UV FP?



- identifying higher order g_n with g_3 possible in both cases
- existence of UV FP in the four-point truncation depends less on closure of the flow equations

Apparent convergence

Summary

- fixed point values change little from $N = 3$ to $N = 4$
- one additional relevant direction for the improved truncation due to R^2
- UV FP becomes generally more stable
 - less dependence on approximation of the stability matrix
 - more freedom for the identification of higher couplings

Conclusion: promising hints towards apparent convergence

Summary and Outlook

systematic vertex expansion up to the graviton four-point function

- closed graviton propagator flow
- identified different diffeomorphism-invariant structures via momentum dependence of n -point functions
- non-trivial UV fixed point
 - three relevant directions corresponding to Λ , R , and R^2
 - connected to GR in the IR
- found promising hints towards apparent convergence

potential next steps:

- include further tensor structures in the vertices, especially of R^2
- look at all graviton modes
- improve bounds for gravity-matter systems

Thank you for your attention!